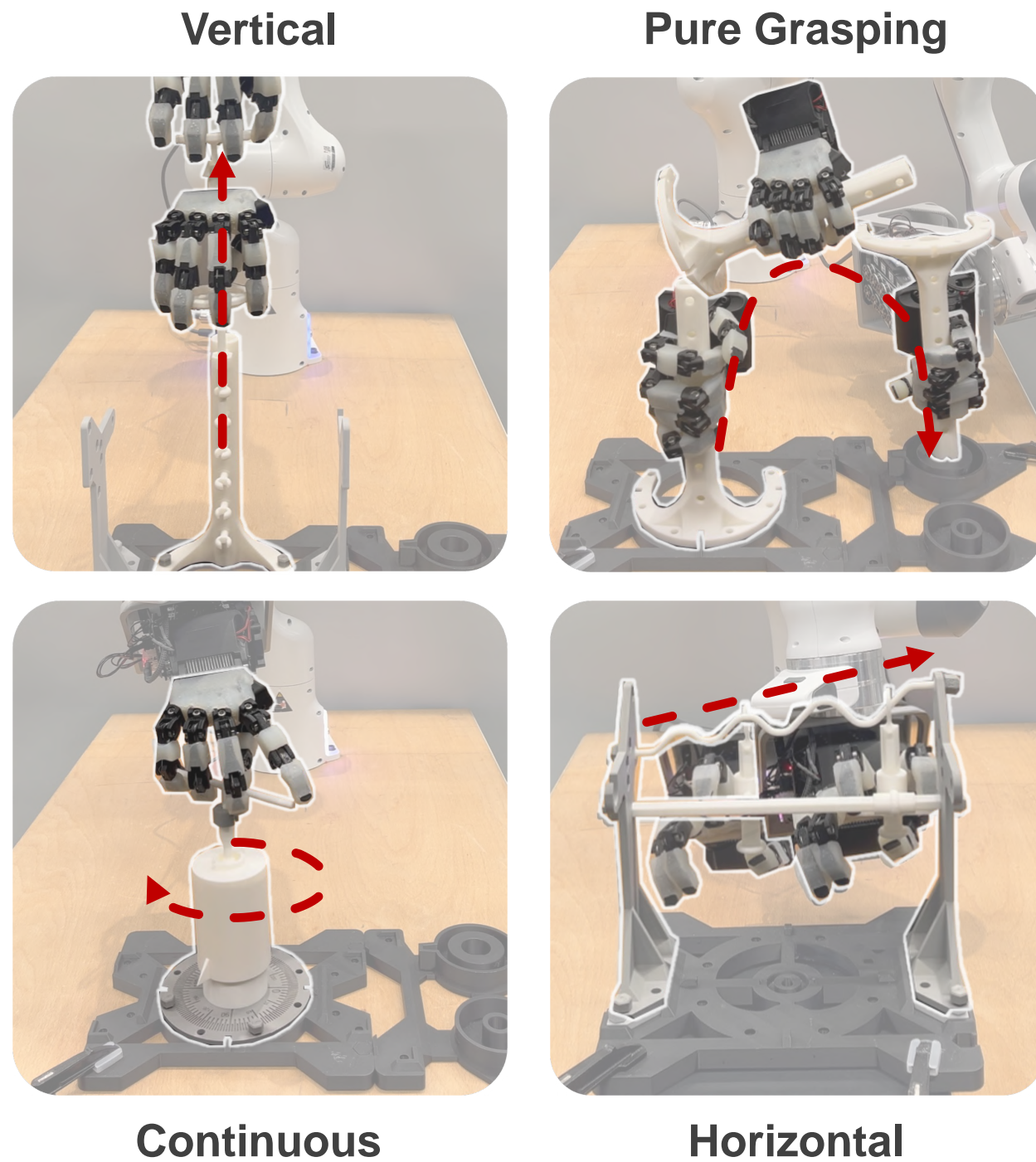


# POMDAR

Performance-based Outcome Measures of Dexterity for Anthropomorphic Robotic Hands

**18** dexterous tasks  
**4** motion configurations



Quantitative Evaluation  
**4** embodiments + **human** baseline

